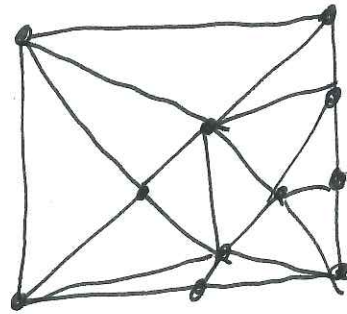
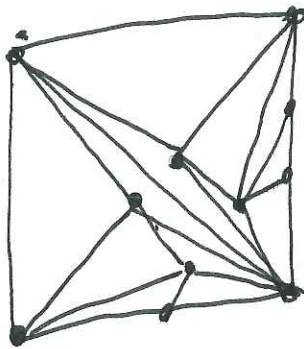


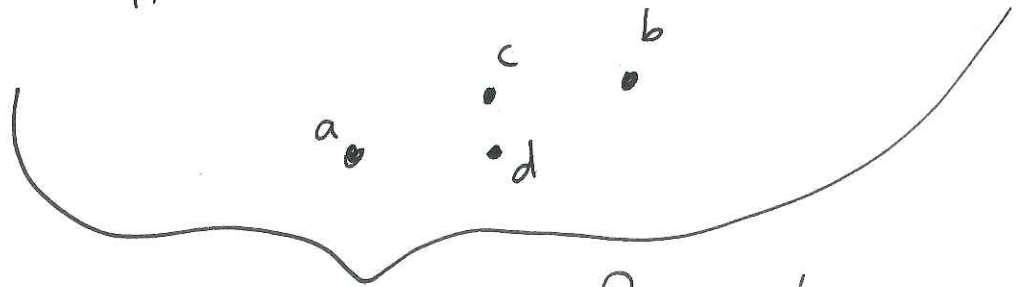
# Why Delaunay?



What makes a good  $\Delta^n$ ?

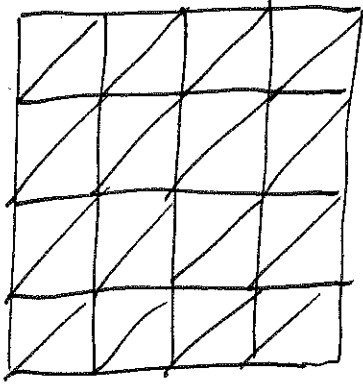
Intuition: (1) Should represent "local" geometry.

(2) Don't connect a to b if other points are in the way.

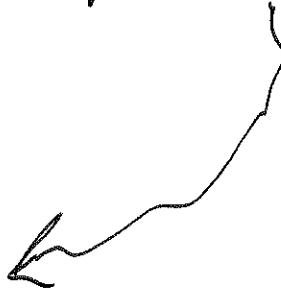
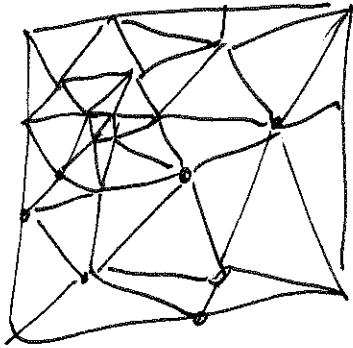


Empty Circle Property

Max-Min Angle Property also helps.



The Delaunay  $\Delta^n$   
is more  
"grid-like" for  
points that may  
not be on a grid.



# Randomized Incremental Delaunay $\Delta^n$ .

RIDel ( $P$ : point set)

Randomly order the points of  $P$

Init  $\Delta^n T$  with an infinite  $\Delta$   $\leftarrow$  requires special predicates.

For  $i = 1$  to  $n$

{ [Find the triangle  $t$  in  $T$  containing  $p_i$ ]  $\leftarrow$  Point Location

$T \leftarrow T.\text{split3ways}(t)$

// Flip  $T$  to Delaunay

push 3 edges of  $t$  onto work\_queue.

while (work\_queue nonempty)

{  $e = \text{work\_queue.pop.}$

If  $e$  is not LD

{  $T \leftarrow T.\text{flip}(e)$

push edges in new  $\Delta$ s to work\_queue

}

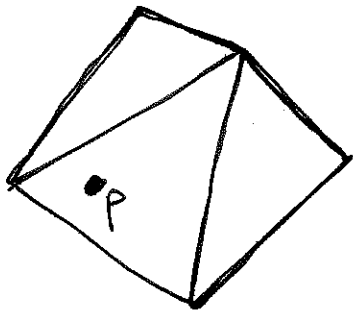
}

}

return  $T$

# Point Location for Randomized Incremental Delaunay $\Delta^n$

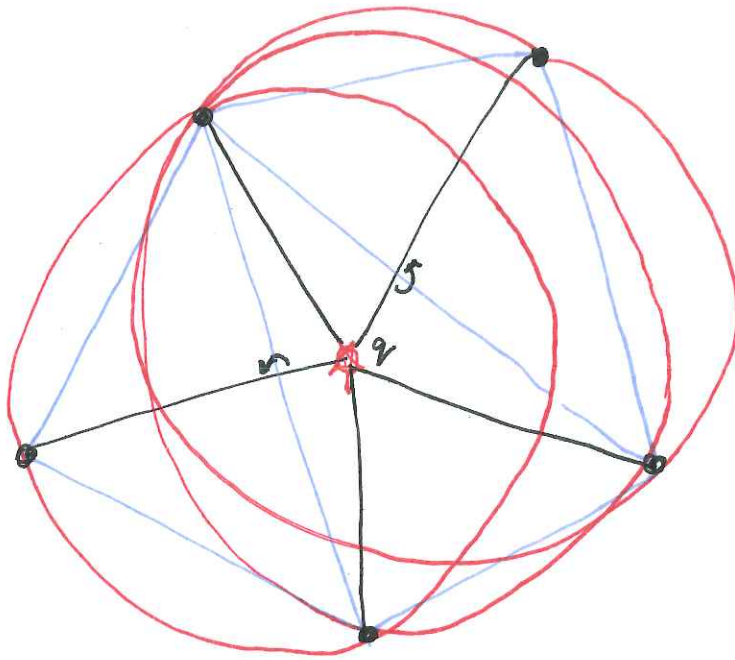
The Problem: To insert a point,  
we need to know what triangle  
contains that point.



The idea: After adding  $p_1, \dots, p_i$ , we  
keep track of which points of  $p_{i+1}, \dots, p_n$   
are in which triangles of  $\text{Delaunay}_{\{p_1, \dots, p_i\}}$ .

Then, when we insert a new point,  
we update for each triangle that was removed.  
Do this locally for each flip.

To Store: For each  $\Delta$ , store a list of uninserted points it contains.  
For each uninserted point, store the triangle that contains it.

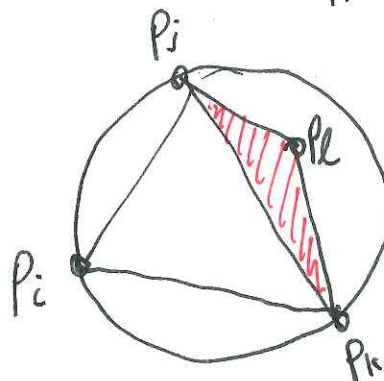
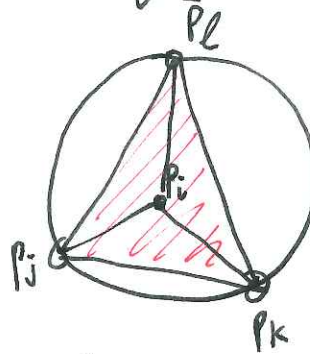
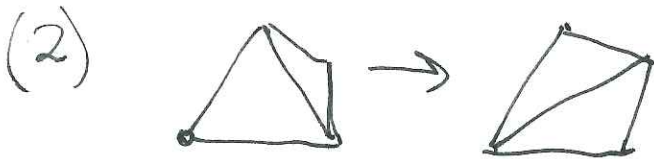
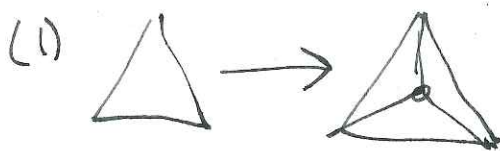


Given  $D_{\text{Del}}$ , we say  $q$  encroaches  $\Delta \in D_{\text{Del}}$  if  $q \in \text{circle}(\Delta)$ .

If we insert  $q$ , all triangles that  $q$  encroaches will be destroyed.

All new triangles have a vertex at  $q$ , otherwise, they were already Delaunay.

### Two ways to destroy a triangle.



Both cases,  $p_i$  is inserted.  $\Delta p_i p_k p_l$  was Del.

$p_l$  work:  
Any points that are moved on  $\text{insert}(p_i)$  are inside  $\text{circle}(p_i p_k p_l)$

Let  $K(\Delta)$  be the points of  $P$  inside circle( $\Delta$ ).

So, point location<sup>(PL)</sup> work is

$$O\left(\sum_{\Delta \in T} |K(\Delta)|\right)$$

Where  $T$  is the set of all triangles appearing in any of the Delaunay triangulations during the course of the algorithm.

$$Q_i = \{p_1, \dots, p_i\}$$

$T_r$  is the set of triangles of Del $_{Q_r}$

$T_r \setminus T_{r-1}$  is the set of "new" triangles added when we added  $p_r$ .

$$k_r(q) = \left| \left\{ \Delta \in T_r : q \in K(\Delta) \right\} \right| \leftarrow \begin{array}{l} \# \text{ of triangles in Del}_{Q_r} \\ \text{that } q \text{ encroaches} \end{array}$$

$$k'_r(q) = \left| \left\{ \Delta \in T_r \setminus T_{r-1} : q \in K(\Delta) \right\} \right| \leftarrow \begin{array}{l} \# \text{ of new triangles} \\ \text{that } q \text{ encroaches} \end{array}$$

$$(1) \quad \sum_{\Delta \in T_r \setminus T_{r-1}} |K(\Delta)| = \sum_{q \in P \setminus Q_r} k'_r(q) \leftarrow \begin{array}{l} \text{standard} \\ \text{double counting} \\ \text{argument} \end{array}$$



$$(2) \quad E[k_r'(q_i)] \leq \frac{3}{r} k_r(q_i)$$

$$E\left[\sum_{q_i \in P \setminus Q_r} k_r'(q_i)\right] \leq E\left[\sum_{q_i \in P \setminus Q_r} \frac{3}{r} k_r(q_i)\right]$$

because each triangle has  $\frac{3}{r}$  chance of being "new".

$$(3) \quad E[k_r(p_{r+1})] = \frac{1}{n-r} E\left[\sum_{q_i \in P \setminus Q_r} k_r(q_i)\right]$$

because each of the  $n-r$  uninserted points are equally likely to be chosen as  $p_{r+1}$ .

$$(4) \quad k_r(p_{r+1}) = |T_r \setminus T_{r+1}|$$

$$= |T_{r+1} \setminus T_r| - 2$$

It's the # of  $\Delta$ s destroyed.  
 $\downarrow$   
 Which is 2 less than the number of new  $\Delta$ s.

$$(5) \quad E[|T_{r+1} \setminus T_r|] < 6$$

By Euler's Formula

$$E \left[ \sum_{\Delta \in T} |K(\Delta)| \right] = E \left[ \sum_{r=1}^n \sum_{\Delta \in T_r \setminus T_{r-1}} |K(\Delta)| \right] \quad [\text{by telescoping (partit)}]$$

$$= \sum_{r=1}^n \sum_{q \in P \setminus Q_r} E[k'_r(q)] \quad [\text{by (1)}]$$

$$\leq \sum_{r=1}^n E \left[ \sum_{q \in P \setminus Q_r} \left(\frac{3}{r}\right) k_r(q) \right] \quad [\text{by (2)}]$$

$$= \sum_{r=1}^n \frac{3(n-r)}{r} E[k_r(p_{r+1})] \quad [\text{by (3)}]$$

$$= 3 \sum_{r=1}^n \left(\frac{n-r}{r}\right) E[|T_{r+1} \setminus T_r| - 2] \quad [\text{by (4)}]$$

$$< 12 \sum_{r=1}^n \left(\frac{n-r}{r}\right) \quad [\text{by (5)}]$$

$$= O(n \log n)$$